

Maximum clique: limits of approximation

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Learning objectives

At the end of this chapter you will be able to:

- ▶ build the strong product of two graphs and prove $\omega(G \boxtimes H) = \omega(G) \omega(H)$;
- ▶ prove that a constant-ratio algorithm for the MCP would give one for every constant ratio;
- ▶ state the results of Håstad and Zuckerman, and conclude that the MCP and the MSSP are not approximable;
- ▶ solve the MCP exactly on planar graphs and on graphs of bounded degree, and approximate the MSSP on graphs of bounded degree.

Prerequisites

- ▶ From this module, the chapter «[Principles of approximation algorithms](#)»: performance ratio for a maximization problem, α -approximation algorithm, PTAS.
- ▶ From this module, the chapter «[Clique problems](#)»: the definitions of the MCP and of the MSSP, the clique number $\omega(G)$, the complement graph and $\omega(G) = \alpha(\overline{G})$.
- ▶ From this module, the chapter «[Vertex coloring: limits of approximation](#)»: planar graphs and the bound $m \leq 3n - 6$.

The problem of this chapter

- ▶ The problem of this chapter is the **maximum clique problem (MCP)**
- ▶ Its definition and its assumptions are on its page
- ▶ The question of the chapter: how well can a **polynomial** algorithm approximate the clique number $\omega(G)$?

Notation

Introduction: Notation

- ▶ In this section we fix the notation on graphs and on the optimal values of the MCP and of the MSSP
- ▶ We recall how the performance ratio is measured for a maximization problem
- ▶ We see which ratio is trivial: the rest of the chapter compares everything with it

Graphs and optimal values

- ▶ As on the problem page, $G = (V, E)$ is a simple graph with n vertices and m edges
- ▶ $N(v)$ is the set of the neighbours of v , and $\Delta(G)$ the maximum degree
- ▶ The optimal value of the MCP is the **clique number**:

$$z(I) = \omega(G)$$

- ▶ The optimal value of the MSSP is the **stability number** $\alpha(G)$

Recall: the performance ratio

- ▶ As in the chapter «Principles of approximation algorithms», $\mathcal{A}(I)$ is the number of vertices of the clique returned by the algorithm $\mathcal{A}$
- ▶ The MCP is a maximization problem, hence

$$\mathcal{A}(I) \leq \omega(G) \quad \text{and} \quad \frac{\omega(G)}{\mathcal{A}(I)} \geq 1$$

for every instance I

The trivial ratio

- ▶ A single vertex is a clique, so the ratio n is trivial
- ▶ This chapter shows that a polynomial algorithm **cannot do much better** on all graphs
- ▶ and then the **classes of graphs** on which it can

Summary: Notation

- ▶ $G = (V, E)$ with n vertices, m edges, neighbourhoods $N(v)$ and maximum degree $\Delta(G)$
- ▶ $z(I) = \omega(G)$ for the MCP, $\alpha(G)$ for the MSSP
- ▶ For a maximization problem the ratio is $\frac{\omega(G)}{\mathcal{A}(I)} \geq 1$
- ▶ One vertex already gives the ratio n

The MCP is not approximable

Introduction: The MCP is not approximable

- ▶ We define the **strong product** of two graphs: it multiplies the clique numbers
- ▶ With it, a constant-ratio algorithm for the MCP would give **every** constant ratio
- ▶ Then we state the results of Håstad and Zuckerman: unless $P = NP$, not even the ratio $n^{1-\varepsilon}$ is possible
- ▶ Together they say that the MCP is **not approximable**

We start from a construction on graphs:
the strong product, which turns two graphs into one.

Definition 1: strong product

The **strong product** of two graphs $G = (V, E)$ and $H = (W, F)$ is the graph $G \boxtimes H$ with vertex set $V \times W$, in which two distinct vertices (u, x) and (v, y) are adjacent if and only if

$$\begin{aligned} & (u = v \text{ or } \{u, v\} \in E) \\ \text{and } & (x = y \text{ or } \{x, y\} \in F). \end{aligned}$$

Size of the product

- ▶ $G \boxtimes H$ has $|V| |W|$ vertices
- ▶ It is built in time polynomial in the size of G and H
- ▶ In particular $G \boxtimes G$ has n^2 vertices

Projection and fibres

For a set $K \subseteq V \times W$:

- ▶ the **projection** is

$$p(K) = \{u \in V : (u, x) \in K \text{ for some } x\}$$

- ▶ the **fibre** of $u \in p(K)$ is

$$K_u = \{x \in W : (u, x) \in K\}$$

- ▶ Projection and fibres take a set of the product apart, one coordinate at a time
- ▶ We now see that they take a clique of the product apart into cliques of the two graphs
- ▶ This is the key fact of the whole chapter

Proposition 1

For every two graphs G and H :

- 1. if $K \subseteq V \times W$ is a clique of $G \boxtimes H$, then $p(K)$ is a clique of G , every fibre K_u is a clique of H , and $|K| \leq |p(K)| \cdot \max_u |K_u|$;*
- 2. $\omega(G \boxtimes H) = \omega(G) \omega(H)$.*

Proof (1/3)

Part 1: the projection is a clique.

- ▶ Let $u \neq v$ be in $p(K)$, with $(u, x), (v, y) \in K$
- ▶ These two vertices are adjacent and $u \neq v$, so $\{u, v\} \in E$
- ▶ Hence $p(K)$ is a clique

Part 1: every fibre is a clique.

- ▶ Let $x \neq y$ be in K_u : (u, x) and (u, y) are adjacent, so $\{x, y\} \in F$
- ▶ Hence K_u is a clique

Proof (2/3)

Part 1: the bound on $|K|$.

- ▶ The fibres split K , hence

$$|K| = \sum_{u \in p(K)} |K_u| \leq |p(K)| \cdot \max_u |K_u|.$$

Proof (3/3)

Part 2.

- ▶ If K_G and K_H are maximum cliques of G and H , every two distinct vertices of $K_G \times K_H$ satisfy the definition, so

$$\omega(G \boxtimes H) \geq \omega(G) \omega(H)$$

- ▶ Conversely, by Part 1 every clique K of $G \boxtimes H$ has

$$|K| \leq |p(K)| \cdot \max_u |K_u| \leq \omega(G) \omega(H)$$



Strong or lexicographic product

- ▶ The *lexicographic* product also satisfies

$$\omega(G[H]) = \omega(G)\omega(H)$$

- ▶ We use the strong product, whose definition is **symmetric** in the two graphs

Now we use the strong product of G with itself to improve the ratio of an approximation algorithm.

From a clique of $G \boxtimes G$ back to G

- ▶ Part 1 of Proposition 1 is **constructive**
- ▶ From a clique K of $G \boxtimes G$, either $p(K)$ or the largest fibre is a clique of G with at least $\sqrt{|K|}$ vertices
- ▶ Indeed, the product of their sizes is at least $|K|$
- ▶ Both are computed in polynomial time

Theorem 1

If the MCP has a polynomial α -approximation algorithm for some constant $\alpha \geq 1$, then it has a polynomial β -approximation algorithm for every constant $\beta > 1$.

- ▶ The idea of the proof: run the algorithm on $G \boxtimes G$, where the optimum is $\omega(G)^2$
- ▶ Go back to G with the square root: the ratio becomes $\sqrt{\alpha}$
- ▶ Repeat a constant number of times

Proof (1/3)

Let $\mathcal{A}$ be a polynomial α -approximation algorithm, and define the algorithm $\mathcal{B}$:

1. build $G \boxtimes G$ and run $\mathcal{A}$ on it, obtaining a clique K ;
2. return the larger of $p(K)$ and of the largest fibre of K , a clique of G with at least $\sqrt{|K|}$ vertices.

Proof (2/3)

- ▶ By Proposition 1, $\omega(G \boxtimes G) = \omega(G)^2$, so

$$|K| \geq \frac{\omega(G)^2}{\alpha}$$

- ▶ and

$$\mathcal{B}(I) \geq \sqrt{|K|} \geq \frac{\omega(G)}{\sqrt{\alpha}}$$

- ▶ $\mathcal{B}$ is a polynomial $\sqrt{\alpha}$ -approximation algorithm

Proof (3/3)

- ▶ Applying the construction t times gives the ratio $\alpha^{1/2^t}$
- ▶ $\mathcal{A}$ is run on a graph with n^{2^t} vertices
- ▶ Choose the constant t with

$$2^t \geq \frac{\ln \alpha}{\ln \beta}$$

- ▶ Then $\alpha^{1/2^t} \leq \beta$, and n^{2^t} is a polynomial



The product amplifies the ratio

- ▶ In other words, the MCP has a constant-ratio algorithm **if and only if** it has a PTAS
- ▶ The strong product *amplifies* any constant ratio
- ▶ The running time grows like a power n^{2^t} , which is polynomial only because t is a constant

This is the positive side of the amplification.
The negative side comes from the theory of complexity.

The results of Håstad and Zuckerman

- ▶ The negative side is known, and we state it **without proof**
- ▶ It uses probabilistically checkable proofs

Theorem 2: Håstad, 1999; Zuckerman, 2007

For every $\varepsilon > 0$, if $P \neq NP$, no polynomial algorithm $\mathcal{A}$ for the MCP satisfies, for every graph G with n vertices,

$$\frac{\omega(G)}{\mathcal{A}(I)} \leq n^{1-\varepsilon}.$$

Two assumptions

- ▶ **Håstad (1999)** proved the theorem under the assumption that NP problems cannot be solved in randomized polynomial time ($NP \neq ZPP$)
- ▶ **Zuckerman (2007)** proved it under $P \neq NP$

No constant ratio and no PTAS

- ▶ As for the VCP, the theorem excludes every constant ratio
- ▶ An α -approximation algorithm has ratio at most $\alpha < n^{1/2}$ on the graphs with $n > \alpha^2$ vertices
- ▶ The smaller graphs are solved by enumeration in constant time
- ▶ Combined with Theorem 1: unless $P = NP$, the MCP has **neither** a constant ratio **nor** a PTAS

The MCP is not approximable

- ▶ The MCP is not approximable: unless $P = NP$, no polynomial algorithm has a constant performance guarantee
- ▶ not even a guarantee of the form $n^{1-\varepsilon}$
- ▶ Positive results exist only on **special classes of graphs**

Summary: The MCP is not approximable (1/2)

Strong product:

- ▶ $G \boxtimes H$ has $|V| |W|$ vertices and $\omega(G \boxtimes H) = \omega(G) \omega(H)$
- ▶ A clique of the product splits into its projection and its fibres, cliques of the two graphs

Amplification:

- ▶ From a clique K of $G \boxtimes G$ we get a clique of G with at least $\sqrt{|K|}$ vertices
- ▶ A constant ratio α gives $\sqrt{\alpha}$, then every constant $\beta > 1$

Summary: The MCP is not approximable (2/2)

Håstad and Zuckerman:

- ▶ Unless $P = NP$, no polynomial algorithm has ratio $n^{1-\varepsilon}$ on every graph
- ▶ Hence the MCP has neither a constant ratio nor a PTAS

Next:

- ▶ Positive results only on special classes of graphs

Special cases

Introduction: Special cases

- ▶ On all graphs the MCP is not approximable, but some classes of graphs are easy
- ▶ On **planar graphs** and on graphs of **bounded maximum degree** the MCP is solved exactly by enumeration
- ▶ Through the complement graph, the negative result passes to the **MSSP**, but the special cases do not
- ▶ On graphs of bounded degree the MSSP has a constant ratio

First class: the planar graphs,
which have no large cliques.

Proposition 2

Every planar graph has $\omega(G) \leq 4$, and on planar graphs the MCP is solved exactly in $O(n^4)$ time.

Proof

- ▶ A subgraph of a planar graph is planar
- ▶ The complete graph with 5 vertices has 10 edges, more than $3 \cdot 5 - 6 = 9$, so it is not planar
- ▶ Hence a planar graph has no clique with 5 vertices
- ▶ The subsets of at most 4 vertices are $O(n^4)$, and each one is checked in constant time



Second class: the graphs of bounded maximum degree,
where every clique stays inside one neighbourhood.

Proposition 3

Every graph has $\omega(G) \leq \Delta(G) + 1$, and the MCP is solved exactly in $O(n 2^{\Delta} \Delta^2)$ time, with $\Delta = \Delta(G)$.

Proof

- ▶ A clique that contains the vertex v is contained in $\{v\} \cup N(v)$, which has at most $\Delta + 1$ vertices
- ▶ For every vertex v , enumerate the $2^{\deg(v)} \leq 2^\Delta$ subsets $S \subseteq N(v)$
- ▶ Keep the largest $\{v\} \cup S$ that is a clique
- ▶ Checking the pairs of S takes $O(\Delta^2)$ time
- ▶ Every maximum clique is found from any of its vertices



When is the time polynomial?

- ▶ The time $O(n 2^\Delta \Delta^2)$ is polynomial for every fixed Δ
- ▶ and even when $\Delta \leq \log_2 n$, since then

$$2^\Delta \leq n$$

What happens to the stable sets?
The complement graph turns one problem into the other.

The maximum stable set problem

- ▶ By $\omega(G) = \alpha(\overline{G})$ (chapter «Clique problems»), a stable set of G is a clique of $\overline{G}$
- ▶ $\overline{G}$ is built in $O(n^2)$ time and has the same n
- ▶ An algorithm with ratio $\rho(n)$ for one of the two problems, applied to the complement graph, has the same ratio $\rho(n)$ for the other one

Corollary 1

For every $\varepsilon > 0$, if $P \neq NP$, no polynomial algorithm for the MSSP has ratio $\frac{\alpha(G)}{\mathcal{A}(I)} \leq n^{1-\varepsilon}$ on every graph. In particular, the MSSP has no constant ratio.

The special cases do not transfer

- ▶ The special cases do *not* transfer to the MSSP
- ▶ The complement of a planar graph, or of a graph of bounded degree, is **dense**
- ▶ On those classes the MSSP remains NP-hard, but it is **approximable**

Proposition 4

*On every graph, a **maximal** stable set S (no vertex can be added to it) has $|S| \geq \frac{n}{\Delta(G)+1}$. Hence the greedy algorithm that adds vertices while possible satisfies*

$$\frac{\alpha(G)}{|S|} \leq \Delta(G) + 1.$$

Proof

- ▶ Every vertex outside S has a neighbour in S , otherwise it could be added
- ▶ Hence

$$V = \bigcup_{v \in S} (\{v\} \cup N(v)) \quad \text{and} \quad n \leq |S| (\Delta(G) + 1)$$

- ▶ Since $\alpha(G) \leq n$, the ratio is at most

$$\frac{\alpha(G)}{|S|} \leq \frac{n}{|S|} \leq \Delta(G) + 1$$



Bounded degree and planar graphs for the MSSP

- ▶ On graphs of maximum degree at most a fixed Δ this is a **constant ratio**
- ▶ On planar graphs the MSSP even has a **PTAS** (Baker, 1994)

Summary: Special cases (1/2)

Planar graphs:

- ▶ K_5 is not planar, so $\omega(G) \leq 4$, and the MCP is solved exactly in $O(n^4)$ time

Bounded maximum degree:

- ▶ $\omega(G) \leq \Delta(G) + 1$: every clique lies in $\{v\} \cup N(v)$
- ▶ Enumeration in $O(n 2^\Delta \Delta^2)$ time, polynomial for fixed Δ or $\Delta \leq \log_2 n$

Summary: Special cases (2/2)

The MSSP:

- ▶ Through $\overline{G}$, the MSSP has no ratio $n^{1-\epsilon}$, unless $P = NP$
- ▶ The special cases do not transfer: the complements are dense
- ▶ A maximal stable set has ratio at most $\Delta(G) + 1$; on planar graphs a PTAS exists

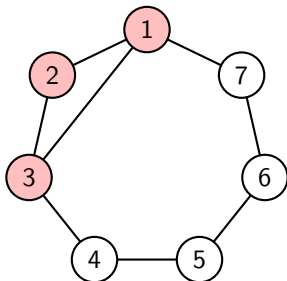
Example

Introduction: Example

- ▶ We apply the results of the chapter to the reference instance of the MCP
- ▶ We see the strong product, a clique of the product taken apart, the enumeration for bounded degree and the bound for planar graphs
- ▶ All the numbers are small enough to be checked by hand

Example (1/4)

- ▶ The reference instance of the MCP is the cycle $1, 2, \dots, 7, 1$ with the chord $\{1, 3\}$
- ▶ $n = 7$, $m = 8$, $\Delta(G) = 3$ and $\omega(G) = 3$, with the unique maximum clique $\{1, 2, 3\}$ (in red)



Example (2/4)

Strong product.

- ▶ $G \boxtimes G$ has $7^2 = 49$ vertices and 240 edges
- ▶ Its clique number is

$$\omega(G \boxtimes G) = 3^2 = 9$$

attained by $\{1, 2, 3\} \times \{1, 2, 3\}$

Example (3/4)

- ▶ Suppose an algorithm returns on $G \boxtimes G$ the clique

$$K = \{1, 2, 3\} \times \{4, 5\}, \quad |K| = 6$$

- ▶ Its projection $p(K) = \{1, 2, 3\}$ and its fibres $K_u = \{4, 5\}$ are cliques of G
- ▶ The larger one has $3 \geq \sqrt{6}$ vertices

Example (4/4)

Bounded degree.

- ▶ The enumeration of Proposition 3 examines

$$\sum_v 2^{\deg(v)} = 2^3 + 2^2 + 2^3 + 4 \cdot 2^2 = 36$$

subsets

- ▶ It finds $\{1, 2, 3\}$ from the vertices 1, 2 and 3

Planarity.

- ▶ The graph is planar, as the figure shows, and $\omega(G) = 3 \leq 4$

Summary: Example

- ▶ On the cycle with a chord, $\omega(G) = 3$ and $\omega(G \boxtimes G) = 9$
- ▶ A clique of 6 vertices of the product gives back a clique of G with $3 \geq \sqrt{6}$ vertices
- ▶ The enumeration for bounded degree examines 36 subsets and finds $\{1, 2, 3\}$
- ▶ The graph is planar, and $\omega(G) = 3 \leq 4$

Sources

Introduction: Sources

- ▶ The results of this chapter come from a textbook and from three research papers
- ▶ They are the places where to read the full proofs, in particular the one of the theorem of Håstad and Zuckerman

Sources (1/2)

- ▶ M.R. Garey, D.S. Johnson, *Computers and Intractability: A Guide to the Theory of NP-Completeness*, W.H. Freeman, 1979 (the self-improvement of the MCP by graph products).
- ▶ J. Håstad, Clique is hard to approximate within $n^{1-\epsilon}$, *Acta Mathematica* 182(1):105–142, 1999.

Sources (2/2)

- ▶ D. Zuckerman, Linear degree extractors and the inapproximability of max clique and chromatic number, *Theory of Computing* 3:103–128, 2007.
- ▶ B.S. Baker, Approximation algorithms for NP-complete problems on planar graphs, *Journal of the ACM* 41(1):153–180, 1994.

Summary: Sources

- ▶ Garey and Johnson (1979): the self-improvement of the MCP by graph products
- ▶ Håstad (1999) and Zuckerman (2007): the ratio $n^{1-\varepsilon}$ is impossible
- ▶ Baker (1994): a PTAS for the MSSP on planar graphs

Typical mistakes

Introduction: Typical mistakes

- ▶ Four mistakes that come up often on the approximation of cliques and stable sets
- ▶ They concern the direction of the ratio, the number of products, and the passage from the MCP to the MSSP
- ▶ Checking them is a quick way to avoid losing points

Observation 1: typical mistakes (1/2)

- ▶ *Inverting the ratio.* The MCP is a maximization problem: the ratio is $\frac{\omega(G)}{\mathcal{A}(I)}$, at least 1.
- ▶ *Iterating the product a number of times that grows with n .* The graph after t products has n^{2^t} vertices: polynomial only for a constant t , so the amplification gives every constant ratio, not the ratio 1.

Observation: typical mistakes (2/2)

- ▶ *Transferring the special cases to the MSSP. The complement of a planar graph is not planar: the MCP is easy on planar graphs, the MSSP is NP-hard there.*
- ▶ *Confusing the bound $\Delta(G) + 1$ of the MCP with that of the MSSP. For the MCP, $\omega(G) \leq \Delta(G) + 1$ bounds the optimum and makes enumeration fast; for the MSSP, $\Delta(G) + 1$ bounds the ratio of a maximal stable set.*

Summary: Typical mistakes

- ▶ The ratio of the MCP is $\frac{\omega(G)}{\mathcal{A}(I)} \geq 1$
- ▶ The number t of products must be a constant
- ▶ Planar graphs are easy for the MCP, not for the MSSP
- ▶ $\Delta(G) + 1$ bounds the optimum of the MCP, and the ratio of a maximal stable set for the MSSP

Summary (1/3)

- ▶ The strong product squares the clique number, and a clique of the product gives back a clique of G of at least the square root of its size: a constant ratio for the MCP would give every constant ratio.
- ▶ By the results of Håstad and Zuckerman, unless $P = NP$ not even the ratio $n^{1-\varepsilon}$ is possible: the MCP is not approximable, and neither is the MSSP, through the complement graph.
- ▶ On planar graphs and on graphs of bounded degree the MCP is solved exactly by enumeration; on graphs of bounded degree a maximal stable set has ratio at most $\Delta(G) + 1$ for the MSSP.

Summary (2/3)

problem and graphs	algorithm	result
MCP, all graphs	any polynomial	no constant ratio, unless $P = NP$
MCP, planar	enumeration	exact, $\omega(G) \leq 4$
MCP, maximum degree $\leq \Delta$	enumeration	exact, $O(n 2^\Delta \Delta^2)$
MSSP, all graphs	any polynomial	no constant ratio, unless $P = NP$
MSSP, maximum degree $\leq \Delta$	maximal stable set	ratio $\leq \Delta + 1$

Summary (3/3)

Dashboard of the reference instance.

Instance	Upper bound	Value found	Optimal value
cycle with a chord	$\Delta(G) + 1 = 4$	3, enumeration	3